

Solutions

1. (a) Eqn 3.29

$$[2] \quad r_t = r_0 e^{-kt} + \theta(1 - e^{-kt}) + \sigma \int_0^t e^{-k(t-s)} dW_s$$

$$[2] \quad (b) \quad Y_T = \int_0^T [(r_0 - \theta)e^{-kt} + \theta] dt + \sigma \int_0^T \left[\int_0^t e^{-k(t-s)} dW_s \right] dt$$

$$[1] \quad \text{Term 1} = \frac{r_0 - \theta}{k} [1 - e^{-kT}] + \theta T$$

$$[1] \quad \text{Term 2} = \sigma \int_0^T \left[\int_s^T e^{-k(t-s)} dt \right] dW_s$$

$$[1] \quad = \frac{\sigma}{k} \int_0^T (1 - e^{-k(T-s)}) dW_s$$

$$[1] \quad \text{Thus } \mu_Y := E[Y_T] = \left(\frac{r_0 - \theta}{k} \right) (1 - e^{-kT}) + \theta T$$

$$[1] \quad \sigma_Y^2 := \text{Var}[Y_T] = \frac{\sigma^2}{k^2} \int_0^T (1 - e^{-k(T-s)})^2 ds \quad (\text{It\^o isometry})$$

$$= \frac{\sigma^2}{k^2} \left[T - \frac{2}{k}(1 - e^{-kT}) + \frac{1}{2k}(1 - e^{-2kT}) \right]$$

$$[1] \quad \mu_r := E[r_T] = (r_0 - \theta)e^{-kT} + \theta$$

$$[1] \quad \sigma_r^2 := \text{Var}[r_T] = \sigma^2 \int_0^T e^{-2k(T-s)} ds = \frac{\sigma^2}{2k} (1 - e^{-2kT})$$

$$[1] \quad \rho \sigma_Y \sigma_r = E[(Y_T - \mu_Y)(r_T - \mu_r)] = \frac{\sigma^2}{k} \int_0^T (1 - e^{-k(T-s)}) e^{-k(T-s)} ds$$

$$[1] \quad = \frac{\sigma^2}{k} \left[\frac{1}{k}(1 - e^{-kT}) - \frac{1}{2k}(1 - e^{-2kT}) \right]$$

[1] Conclude $(r_T, Y_T) \sim N(\mu, \Sigma)$

$$\mu = \begin{bmatrix} \mu_r \\ \mu_Y \end{bmatrix}, \quad \Sigma = \begin{bmatrix} \sigma_r^2 & \rho \sigma_Y \sigma_r \\ \rho \sigma_Y \sigma_r & \sigma_Y^2 \end{bmatrix}$$

$$1c) \text{ Let } Z_t = E \left[\frac{dQ^T}{dQ} \mid \mathcal{F}_t \right] := e^{\int_0^t (\phi_s dW_s^\alpha - \frac{1}{2} \phi_s^2 ds)} \quad (2)$$

Then $-\phi_t$ is drift of W^α under Q^T .

$$\text{Then } Z_t = E \left[\frac{e^{-Y_T}}{P_0(T)} \mid \mathcal{F}_t \right] = e^{-Y_t} \times E \left[\frac{e^{-(Y_T - Y_t)}}{P_0(T)} \mid \mathcal{F}_t \right]$$

Note $Y_T - Y_t = \left(\frac{r_t - \theta}{R} \right) (1 - e^{-k(T-t)}) + \text{a term indep. of } \mathcal{F}_t$

$$\therefore Z_t = e^{-Y_t - \frac{1}{R} (1 - e^{-k(T-t)}) r_t} \times \text{deterministic fn.}$$

$$\text{Now } dZ_t = Z_t \left[\underbrace{-dY_t - \frac{\sigma}{R} (1 - e^{-k(T-t)})}_{\text{pure drift}} dW_t^\alpha + \text{pure drift} \right]$$

$$= \phi_t Z_t dW_t^\alpha$$

$$\therefore \boxed{-\phi_t = + \frac{\sigma}{R} (1 - e^{-k(T-t)})} = \text{drift of BM } W^\alpha \text{ under } Q^T.$$

Alternative $Z_t = \frac{e^{-Y_t} \cdot e^{A(t,T) + B(t,T)r_t}}{e^{A(0,T) + B(0,T)r_0}} \quad (\text{Prop 3.2.2})$

$$dZ_t = Z_t \left[B(t,T) dr_t + \text{drift terms} \right].$$

$$[3] \quad \therefore \phi_t = \sigma B(t,T) = \frac{\sigma}{R} \left[e^{-k(T-t)} - 1 \right] = -\text{drift of BM.}$$

2

$$E_t = \text{BS call}(A_t, K, r, \sigma, T-t) = S_t N. \quad (*)$$

③

$$dE_t = \frac{\partial E_t}{\partial A} dA_t + \frac{\partial E_t}{\partial t} dt + \frac{1}{2} \frac{\partial^2 E_t}{\partial A^2} d[A, A]_t$$

$$= N(d_{1,t}) \cdot \sigma A_t dW_t^0 + \text{drift}$$

$$= \sigma_t^{(s)} E_t dW_t^0 + \text{drift}$$

$$\therefore \sigma_t^{(s)} = \frac{\sigma A_t N(d_1)}{E_t}$$

[3]

where E_t given by (*)

$$d_1(A, K, r, \sigma, T-t) = \frac{\log(A/K) + (r + \frac{\sigma^2}{2})(T-t)}{\sigma \sqrt{T-t}}$$

For fixed K, r, σ let $F(A, t) = \text{BS call}(A, K, r, \sigma, t)$

for $t > 0$. $F(A, t)$ is monotone increasing in A

$$F(-\infty, t) = 0, \quad F(+\infty, t) = +\infty$$

Let $A = G(x, t)$ be solution of $F(A, t) = x$, $x \in (0, \infty)$

$$\text{Then } f(T-t, S) = \frac{\sigma G(N(S, T-t)) N(d_1)}{NS}$$

[1]

where $d_1 = d_1(G(N(S, T-t)), K, r, \sigma, T-t)$

$$\therefore \frac{dS_t}{S_t} = r dt + f(T-t, S_t) dW_t^0$$

Yes S_t is a Markov process, since it solves

[1]

an Ito SDE of type Eqn A.1

(Note: SDE is not time-homogeneous).

3. (a) $P[\tau > t | \mathcal{F}_s] = E[H_t^c | \mathcal{F}_s] = H_s^c E[e^{-\int_s^t \lambda_u du} | \mathcal{F}_s]$
 [2]

[2] $= H_s^c f(t-s, r_s, \lambda_s, 0, 1)$

(b) $\bar{P}_t^0(T) = E[H_T^c e^{-\int_t^T r_s ds} | \mathcal{F}_t] = H_t^c E[e^{-\int_t^T (r_s + \lambda_s) ds} | \mathcal{F}_t]$
 [2]

[2] $= H_t^c f(T-t, r_t, \lambda_t, 1, 1)$

(c) f , by Feynman-Kac, solves
 NOTE: sign change because of $T-t$

[3]
$$\begin{cases} -\partial_t f + \mathcal{L}f - (ur+vl)f = 0, t > 0 \\ f(0, r, \lambda, u, v) = 1 \end{cases}$$

where $\mathcal{L}f = (a-br)\partial_r f + (a'-b'r-c'\lambda)\partial_\lambda f$

[1] $+ \frac{1}{2} [\sigma^2 r^2 \partial_r^2 f + \sigma'^2 \lambda^2 \partial_\lambda^2 f]$

$(- \dot{A} - \dot{B}r - \dot{C}\lambda) + (a-br)B + (a'-b'r-c'\lambda)C$

[1] $+ \frac{1}{2} [\sigma^2 r^2 B^2 + \sigma'^2 \lambda^2 C^2] - (ur+vl) = 0$

[2]
$$\begin{cases} \dot{A} = aB + a'C, & A(0) = 0 \\ \dot{B} = -bB - b'C + \frac{1}{2} \sigma^2 B^2 - u = 0, & B(0) = 0 \\ \dot{C} = -cC + \frac{1}{2} \sigma'^2 C^2 - v = 0, & C(0) = 0 \end{cases}$$