

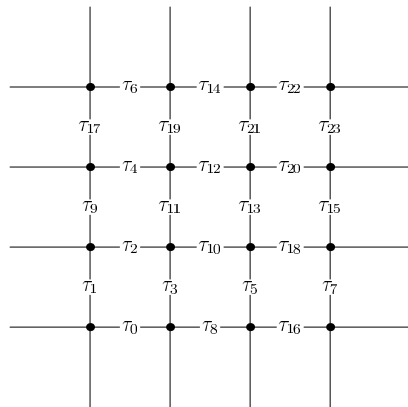
Variational Formula for First Passage Percolation

Arjun Krishnan

Fields Institute, Toronto.
(work done in the Courant Institute, New York)

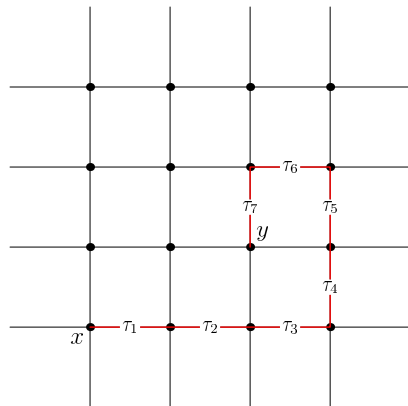
Fields Postdoc Seminar, Oct 16 2014

First Passage Percolation on the Lattice



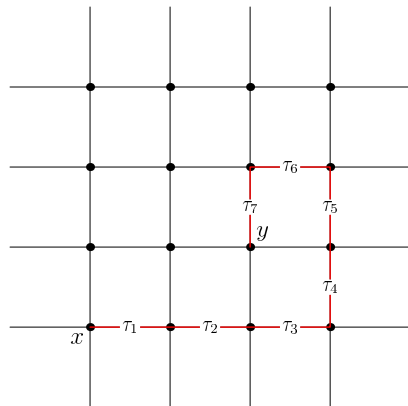
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First Passage Percolation on the Lattice



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- ▶ Path $\gamma(x, y)$ has total weight $W(\gamma(x, y)) = \text{sum of edge-weights}$

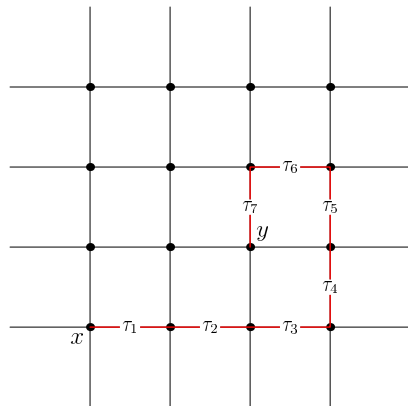
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$$T(x, y) = \inf_{\gamma} W(\gamma(x, y))$$

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- ▶ First-Passage Time:
$$T(x, y) = \inf_{\gamma} W(\gamma(x, y))$$
- ▶ Will write $T(x)$ for $T(x, 0)$ in general

What do we want to compute?

Time-constant $g(x)$

- ▶ Fix $x \in \mathbb{R}^d$, consider an “average” time to travel in direction x .

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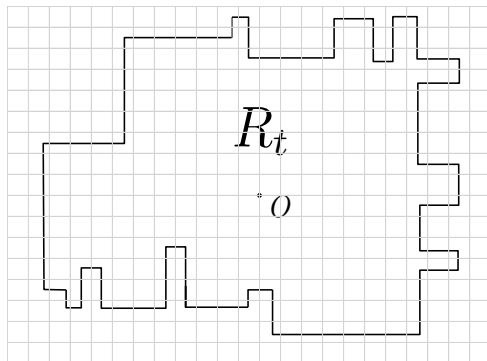
- ▶ $g(x)$ is called time-constant.

Motivation: the limit-shape

Consider sites occupied by time t :

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We're interested in the limiting behavior of this set.



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Theorem [Cox and Durrett, 1981]

$$\lim_{t \rightarrow \infty} R_t/t = \{x : g(x) \leq 1\}$$

What do we prove?

Time constant solves a PDE

- ▶ Movement of light in a medium: Eikonal equation.

$$c(x)|Du(x)| = 1, \quad u(0) = 0$$

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- ▶ $g(x)$ is a norm on \mathbb{R}^d
- ▶ By convex duality $H(p)$ is the dual norm:

$$H(p) = \sup_{g(x)=1} x \cdot p$$

Notation for edge-weights

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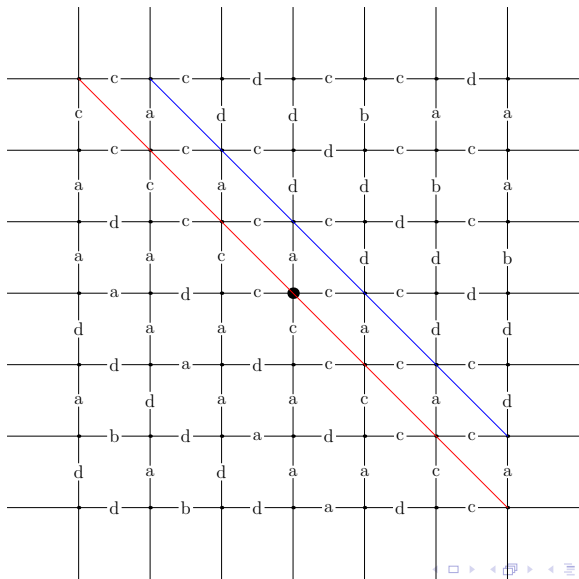
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- ▶ $\tau(z, \alpha, \cdot)$ represents edge-weight at $z \in \mathbb{Z}^d$ in the $\alpha \in A$ direction
- ▶ Weights are stationary and ergodic (e.g. i.i.d.), and they're uniformly bounded (away from 0 and from above)

Assume symmetry in the medium (only for the examples)

$\tau(x, \alpha, \omega) \in \{a, b, c, d\}$, $\alpha \in \{\pm e_1, \pm e_2\}$

$\tau(\cdot, \cdot, \omega)$ is constant along $x + y = z$.



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- ▶ Will see the level sets $\{p \in \mathbb{R}^2 : H(p) = 1\}$.

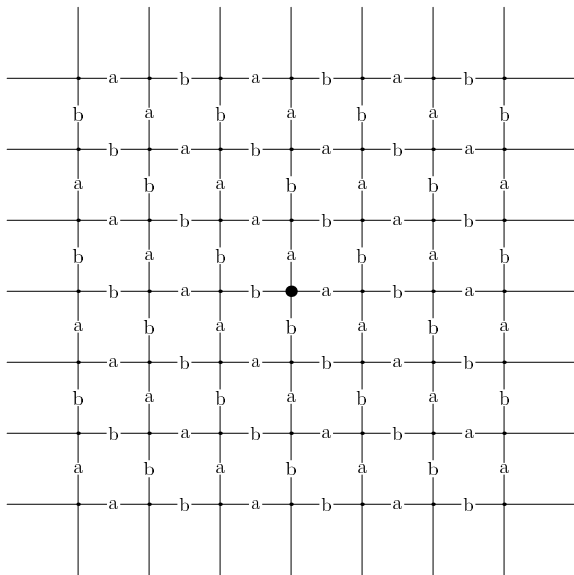
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- ▶ Will play around with edge-weight marginals; all supported on $[1, 2]$. All will have $E[\tau] = 1.5$.
- ▶ Will see the level sets $\{p \in \mathbb{R}^2 : H(p) = 1\}$.
- ▶ The “bigger” the Hamiltonian level-set, the slower the percolation. It’s a speed-time duality.

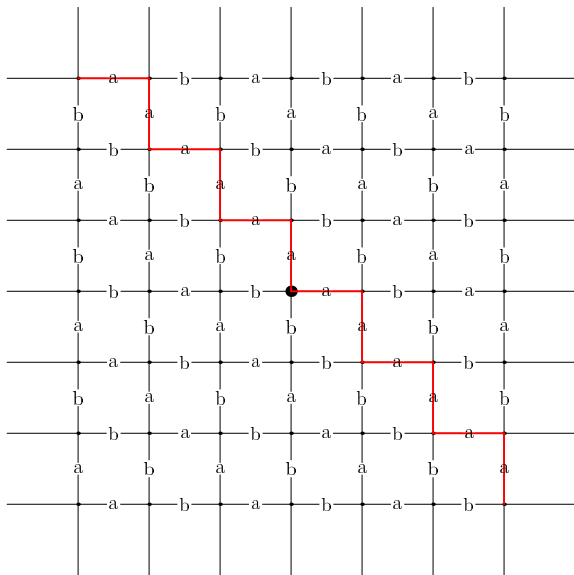
Example: Periodic Medium

$\tau(\cdot, \cdot, \omega) \in \{a, b\}, a < b$



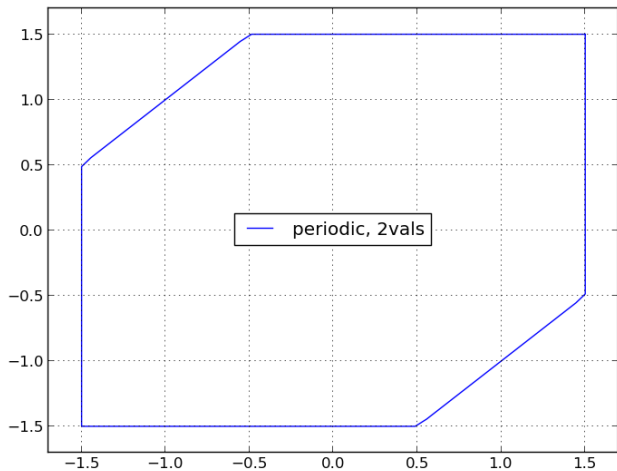
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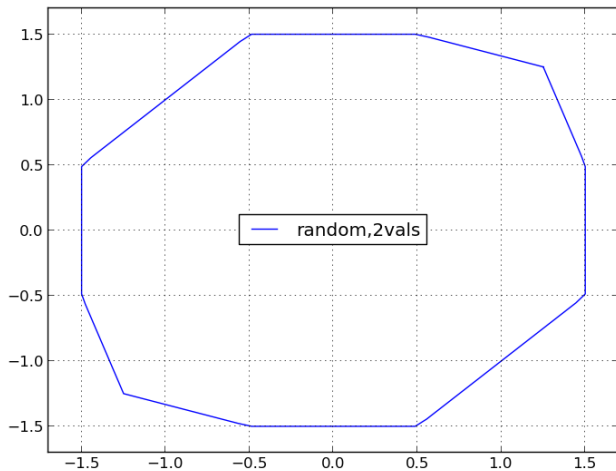
Limit Shape: Periodic Medium

$\tau \in \{1, 2\}$, Plot of $H(p) = 1$



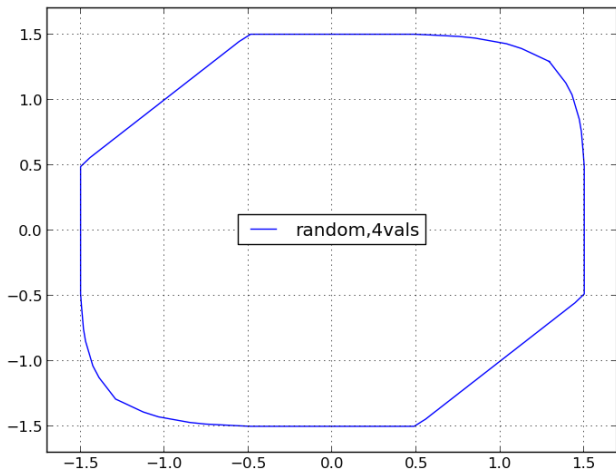
Limit Shape: Comparing different media

$\tau \in \{1, 2\}$, uniform measure, plot of $H(p) = 1$



Limit Shape: Comparing different media

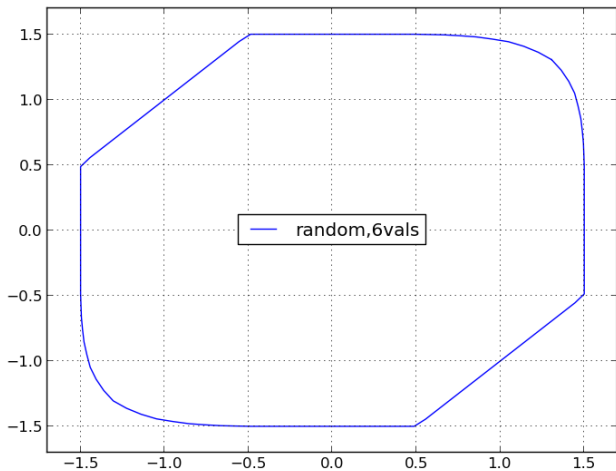
$\tau \in \{1, 1.33, 1.66, 2\}$, uniform measure, plot of $H(\rho) = 1$



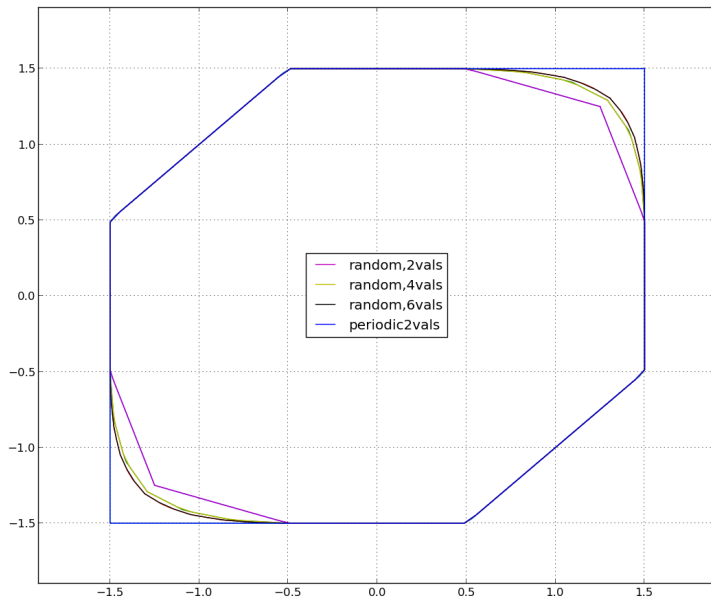
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$\tau \in \{1, 1.2, 1.4, 1.6, 1.8, 2\}$, uniform measure, plot of $H(p) = 1$



Limit Shape: Comparing different media



Outline

A middle-of-the-talk outline

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- ▶ Proof sketch
- ▶ Future work/other applications

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- ▶ Exact limit shapes can be calculated for two special edge-weight distributions Johansson [2000], Seppäläinen [1998].
- ▶ KPZ scaling and fluctuations (in $d = 2$):

$$T([nx]) \sim g(x)n + n^{1/3}\xi$$

ξ is a random variable that's Tracy-Widom distributed (from random matrix theory) [Johansson, 2000]. Is it universal?

Notation for main theorem

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- ▶ For $f : \mathbb{Z}^d \rightarrow \mathbb{R}$, discrete derivative is
$$Df(x, \alpha) = f(x + \alpha) - f(x).$$
- ▶ Will optimize functions f , such that $E[Df] = 0$, Df stationary.

Main Theorem

Variational Formula

Theorem

For $p \in \mathbb{R}^d$, the dual norm of $g(x)$ is given by

$$H(p) = \inf_{f \in S} \operatorname{ess\,sup}_{\omega \in \Omega} \mathcal{H}(Df + p, x, \omega),$$

where

\mathcal{H} is the discrete Hamiltonian

S is a set of functions.

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where

$$\mathcal{H}(Df + p, x, \omega) = \sup_{\alpha \in A} \left\{ -\frac{Df(x, \alpha) + p \cdot \alpha}{\tau(x, \alpha, \omega)} \right\},$$
$$S = \left\{ f: \mathbb{Z}^d \rightarrow \mathbb{R} \mid E[Df] = 0, Df \text{ stationary} \right\}.$$

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- ▶ Had a sequence of minimization problems $T_n(x)$; minimization was over paths
- ▶ Replace this with a single variational problem for $H(p)$; minimization over functions
- ▶ Think of this is a nonlinear duality principle:

$$\begin{aligned}g(x) &= \lim_{n \rightarrow \infty} \frac{1}{n} \inf_{\text{paths}} (\text{"convex fn"}) \\ &= \sup_{f \in S} (\text{"Legendre transform"})\end{aligned}$$

Application

Exact limit-shape by iteration

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Symmetry Assumption

For each $z \in \mathbb{Z}$, assume

$$\tau(x, \cdot, \omega) = \tau(y, \cdot, \omega) \quad \forall x + y = z.$$

Algorithm to produce a minimizer

Theorem: constructing the minimizer

For any $f_0 \in S$, we give an explicit $\mathcal{I} : S \rightarrow S$ such that the sequence defined by

$$f_{n+1} = \mathcal{I}(f_n),$$

converges to a minimizer.

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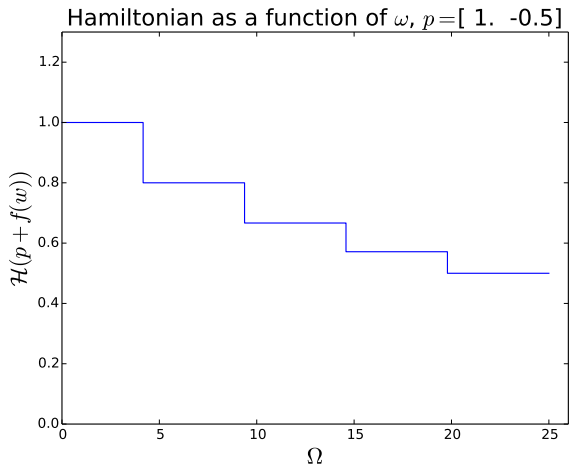
Proof implies

One of the following happens:

- ▶ Algorithm terminates in finite time at a corrector
- ▶ Algorithm terminates in finite-time at a generic minimizer
- ▶ Algorithm continues to infinity, produces corrector in limit

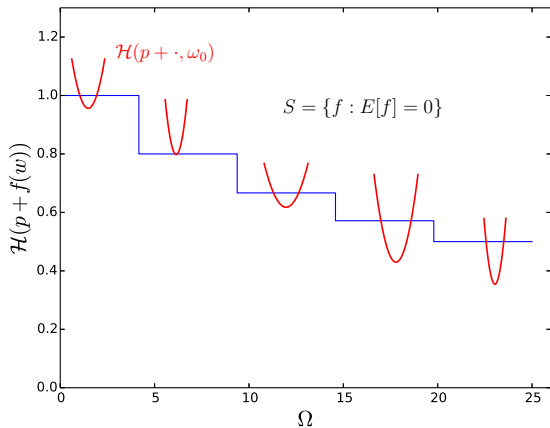
Algorithm in action

Show animation of algorithm in action



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Proof sketch: where does the PDE come from?

The local characterization

- ▶ Dynamic Programming Principle:

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- ▶ Introduce scaling: $T_n(x) := T([nx])/n$, get homogenization problem

$$\mathcal{H}(DT_n(x), [nx]) + O(n^{-1}) = 1, \quad T_n(0) = 0.$$

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- ▶ Take a limit as $n \rightarrow \infty$, and show

$$H(Dg(x)) = 1.$$

Two different viewpoints in continuum

Viewpoint 1: Rezakhanlou and Tarver [2000], Kosygina, Rezakhanlou, and Varadhan [2006]

- ▶ Has flavor of duality principle, uses minimax theorem.
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Discrete versions

Krishnan [2013], Georgiou, Rassoul-Agha, and Seppäläinen [2013].

The cell-problem and the multiple scales ansatz

Homogenization problem

Given

$$\mathcal{H}(Du_\epsilon, \epsilon^{-1}x) = 1, \quad u_\epsilon(0) = 0.$$

$u_\epsilon(x) \rightarrow u(x)$ as $\epsilon \rightarrow 0$?

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Cell problem

For fixed $p \in \mathbb{R}^d$, can you find $v(y)$ with sublinear growth such that

$$\mathcal{H}(p + Dv(y), y) = 1$$

Proof sketch: some issues

Local characterization not sufficient

Consider first-passage percolation with constant edge-weights in one dimension.

$$|T(x+1) - T(x)| = 1 \quad \forall x \in \mathbb{Z}, \quad T(0) = 0$$

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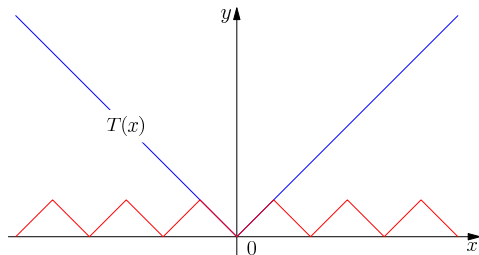
Problem

Solution is non-unique.

Proof sketch

Uniqueness problem

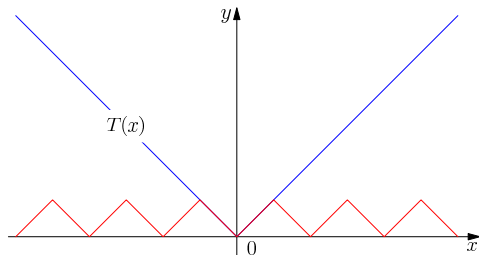
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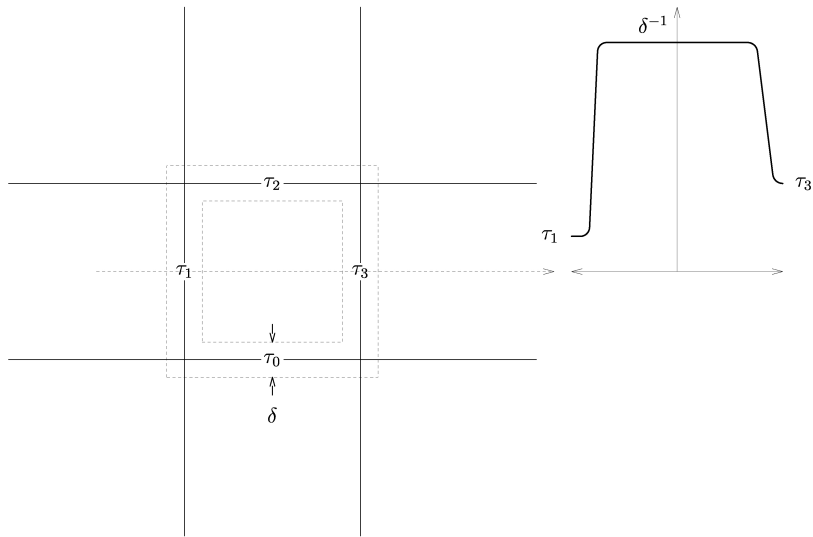


However

Solved in continuum by choosing viscosity solution.

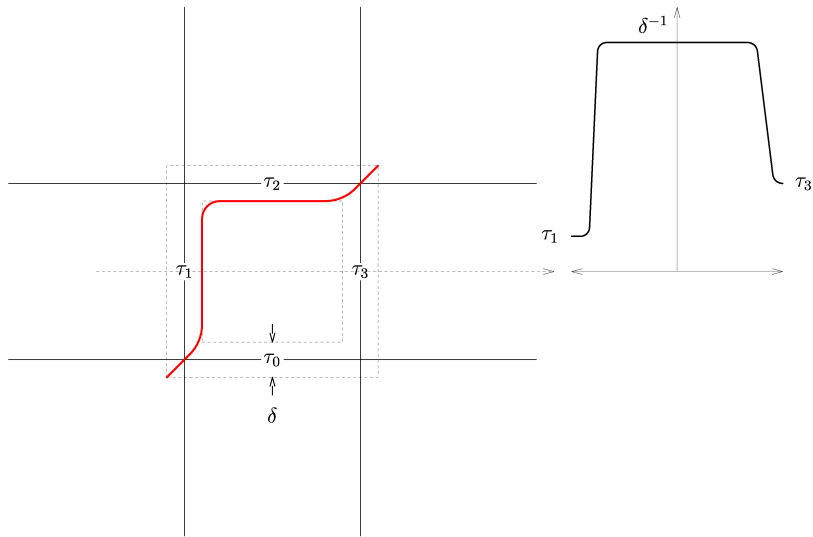
Take problem into continuum

Make edge-weight function $\tau_\delta(x)$



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Iteration and Regularity

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- ▶ Strict convexity of $H(p) \Leftrightarrow$ regularity of $g(x)$.
Use iteration to prove existence of correctors, uniqueness of minimizer and hence strict convexity of $H(p)$?
- ▶ I believe this is possible for monotone Hamiltonians (directed first-passage percolation, polymer models).

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Fluctuations

- ▶ As stated earlier, model is conjecturally in the KPZ universality class: (both scale and fluctuations)

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ξ is Tracy-Widom distributed.

- ▶ First step is to get the right scale of fluctuations (best known upper bound is $(n/\log(n))^{1/2}$ due to Benjamini et al. [2003]).

Acknowledgements

- ▶ S. Chatterjee, S.R.S Varadhan, R.V. Kohn

Acknowledgements

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